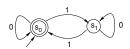
- Finite directed graph
- Edges (transitions) labeled with symbols from an alphabet
- Nodes (states) labeled only for convenience
- One initial state
- Several accepting states



• A string $c_1 c_2 c_3 \dots c_n$ is accepted by a state transition diagram if there exists a path from the starting state to an accepting state such that the sequence of labels along the path is c_1, c_2, \ldots, c_n

$$\xrightarrow{c_1} \xrightarrow{c_2} \xrightarrow{c_3} \xrightarrow{c_n} \xrightarrow{c_n} \bigcirc$$

- Same state might be visited more than once
- Intermediate states might be accepting (but it does not matter)
- The set of exactly all the strings accepted by a state transition diagram is the language accepted (or recognized) by the state transition diagram

State Transition Diagrams (S. D. Bruda)

CS 310, Winter 2025 1 / 11

DETERMINISTIC FINITE AUTOMATA

 A state diagram describes graphically a deterministic finite automaton (DFA), a machine that at any given time is in one of finitely many states, and whose state changes according to a predetermined way in response to a sequence of input symbols

State Transition Diagrams

Stefan D. Bruda

CS 310, Winter 2025

- Formal definition: a deterministic finite automaton is a tuple $M = (K, \Sigma, \delta, s, F)$
 - $K \Rightarrow$ finite set of states
 - $\Sigma \Rightarrow$ input alphabet
 - $F \subseteq K \Rightarrow$ set of accepting states
 - $s \in K \Rightarrow$ initial state
 - $\delta: K \times \Sigma \to K \Rightarrow$ transition function

SOFTWARE REALIZATION

- Big practical advantages of DFA: very easy to implement:
 - Interface to define a vocabulary and a function to obtain the input tokens

```
/* alphabet + end-of-string */
typename vocab;
                      /* end-of-string pseudo-token */
const vocab EOS:
vocab gettoken(void); /* returns next token */
```

• Variable (state) changed by a simple switch statement as we go along

```
int main (void) {
   typedef enum {S0, S1, ... } state;
                    vocab t = gettoken();
   state s = S0;
   while (t != EOS) {
       switch (s) {
           case S0: if (t == ...) s = ...; break;
                     if (t == ...) s = ...; break;
           case S1: ...
            . . .
       } /* switch */
       t = gettoken(); } /* while */
    /* accept iff the current state s is final */
```

}

 $= q_2$

 $= q_4$

 $= q_1$

CS 310, Winter 2025 3 / 11



typedef enum {ZERO, ONE, EOS} vocab;

```
vocab gettoken(void) {
    int c = getc(stdin);
    if (c == '0') return ZERO;
    if (c == '1') return ONE;
    if (c == ^{n}) return EOS;
    perror("illegal character");
                                    }
int main (void) {
    typedef enum {S0, S1 } state;
    state s = S0;
                    vocab t = gettoken();
    while ( t != EOS ) {
        switch (s) {
            case S0: if (t == ONE) s = S1; break;
                  /* if (t == ZERO) s = S0; break */
            case S1: if (t == ONE) s = S0; break;
                  /* if (t == ZERO) s = S1; break */ } /* switch */
        t = gettoken(); } /* while */
    if (s != S0) printf("String not accepted.\n");
                                                       }
```

NONDETERMINISM

- So far the state diagrams are deterministic = for any pair (state, input symbol) there can be at most one outgoing transition
- A nondeterministic diagram allows for the following situation:
- The acceptance condition remains unchanged:
 - A string $c_1 c_2 c_3 \dots c_n$ is accepted by a state transition diagram if there exists some path from the starting state to an accepting state such that the sequence of labels along the path is c_1, c_2, \dots, c_n
- Why nondeterminism?

State Transition Diagrams (S. D. Bruda

• Simplifies the construction of the diagram

$$\Sigma (q_0) \xrightarrow{\mathsf{m}} (q_1) \xrightarrow{\mathsf{a}} (q_2) \xrightarrow{\mathsf{n}} (q_3)$$

- A nondeterministic diagram can be much smaller than the smallest possible deterministic state diagram that recognizes the same language
- Also known as nondeterministic finite automata (NFA)

CS 310, Winter 2025 4 / 11

SOFTWARE REALIZATION

State Transition Diagrams (S. D. Bruda)

3

As above, except that we have to keep track of a set of states at any given time
 typedef enum { Q0, Q1, Q2, Q3 } state;
 int main (void) {
 vocab t = gettoken(); StateSet A; A.include(Q0);
 while (t != EOS) {

SOFTWARE REALIZATION (CONT'D)

- This kind of implementation is fine for "throw-away" automata
 - Text editor search function searches for a pattern in the text
 - The next search is likely to be different so a brand new automaton needs to be created
- Some times the automaton is created once and then used multiple times
 - The lexical structure of a programming language is well established
 - Lexical analysis in a compiler is accomplished by an automaton that never changes
 - In such a case it is more efficient to precalculate the set of states
 - Exactly as in the previous program
 - Except that we no longer have an input to guide us, so we calculate the sets NewA for all possible inputs
 - We obtain a DFA that is equivalent to the given NFA (i.e., recognizes the same language)

CS 310, Winter 2025 5 / 11

PRECALCULATING STATE SETS

 ε -TRANSITIONS

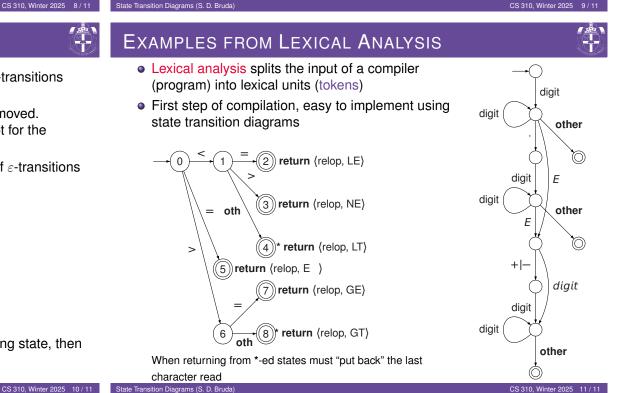
 Precalculating all the sets of states effectively constructs a deterministic state transition diagram that is equivalent to the original (nondeterministic) state transition diagram:

```
algorithm DETERMINIZE(M = (K, \Sigma, \Delta, s, F)) returns M' = (K', \Sigma, \delta', s', F'):
               S \leftarrow \{\{s\}\}
                                                                                                 (active states)
               K' \leftarrow \emptyset
                                                                                                  (done states)
               \delta' \leftarrow \emptyset
                                                                                  (start with no transitions)
               while S \neq \emptyset do
                     Choose A \in S
                                                                                            (any state will do)
                     S \leftarrow S \setminus \{A\}
                     K' \leftarrow K' \stackrel{?}{\cup} \{A\}
                                                                                  (state A processed now)
                    foreach a \in \Sigma do
                                                         (each action will lead to a new state NewA)
                           NewA \leftarrow \emptyset
                          foreach (p, a, q) \in \Delta \land p \in A do
                                NewA \leftarrow NewA + q (for every p in A and p \xrightarrow{a} q we add q)
                          if NewA \neq \emptyset then (if NewA is empty then there is no transition)
                                 Add to \delta' transition A \xrightarrow{a} NewA
                                if NewA \notin S \cup K' then
                                                                   if NewA is processed we are done
                                  | S \leftarrow S \cup \{NewA\}
                                                                     (otherwise we add it to the queue)
               s' \leftarrow \{s\}
               F' \leftarrow \{ p \in K' : K' \cap F \neq \emptyset \}
                                                                        (a single accepting state will do)
State Transition Diagrams (S. D. Bruda
```

- Useful at times to have "spontaneous" transitions = transitions that change the state without any input being read = ε -transitions
 - Only available for nondeterministic state transition diagrams!
- Example of usefulness: Construct the state transition diagram for the language

 $\{0,1\}^*01\{0,1\}^* + \{w \in \{0,1\}^* : w \text{ has an even number of } 1's\}$

Even better ε-transitions can be eliminated afterward



ELIMINATING ε -TRANSITIONS

For every diagram M with ε -transitions a new diagram without ε -transitions can be constructed as follows:

- **(1)** Make a copy M' of M where the ε -transitions have been removed. Remove states that have only ε -transitions coming in except for the starting state
- 2 Add transitions to M' as follows: whenever M has a chain of ε -transitions followed by a "real" transition on x:



add to M' a transition from state q to state p labeled by x:

 $(q) \xrightarrow{x} (p)$

- Note that q and p may be any states
- In particular this step is also used in the case where q = p
- If M has a chain of ε -transitions from a state r to an accepting state, then r is made to be an accepting state of M'.