

CS 316: Prolog

Stefan D. Bruda

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PROLOG



- Widely used in Europe and Japan
- Basis of the 5-th Generation project
- FOL inference system
- Knowledge base represented using Horn clauses
 - Program: set of (Horn) clauses.
 - Input data: queries (i.e., FOL sentences to be proved)
 - Output: failure or success + variable bindings
- Uses input modus ponens for proofs
 - more precisely, depth-first, left-to-right backward chaining
 - returns on request all the possible solutions
- Uses database semantics instead of the general FOL semantics

SYNTAX



- Atoms: constants (including function names and predicate names)
 - Everything **not** starting with a capital letter or underscore, and everything surrounded by simple quotes is an atom
- Variables: everything starting with a capital letter or underscore
- Convenient notation for lists:
 $\langle a, b \rangle \rightsquigarrow [A|B]$ $\langle \text{Joe}, \langle \text{Jack}, \langle \text{Jill}, [] \rangle \rangle \rangle \rightsquigarrow [\text{joe}, \text{jack}, \text{jill}]$.
- Clauses: **facts**

```
parent(ann,bob).           parent(cecil,dave).  
parent(ann,cecil).         parent(cecil,eric).
```


and **rules** (with all variables universally quantified)

```
ancestor(A,B) :- parent(A,B).  
ancestor(A,C) :- ancestor(A,B), ancestor(B,C).
```
- Queries: FOL sentences (with all variables existentially quantified)

DATABASE SEMANTICS



- Suppose Richard has two brothers, John and Geoffrey:

$\text{Brother}(\text{John}, \text{Richard}) \wedge \text{Brother}(\text{Geoffrey}, \text{Richard})$

- This assertion is always true in a model where Richard has one brother, so we need to add $\text{John} \neq \text{Geoffrey}$
- The sentence does not rule out that Richard has more than two brothers
- The correct assertion therefore is:

$\text{Brother}(\text{John}, \text{Richard}) \wedge \text{Brother}(\text{Geoffrey}, \text{Richard}) \wedge$
 $\text{John} \neq \text{Geoffrey} \wedge$
 $\forall x \text{ Brother}(x, \text{Richard}) \Rightarrow (x = \text{John} \vee x = \text{Geoffrey})$

- Things get complex pretty fast, translating knowledge into knowledge bases becomes exceedingly difficult
- We can use a semantics that provides for more straightforward expressions: **database semantics**



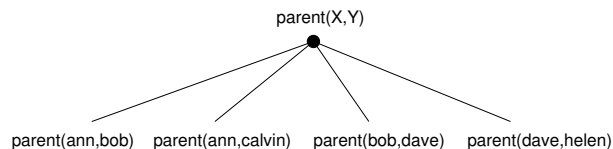
- **Unique-names assumption:** every constant symbol refers to a distinct object
 - Breaks down skolemization but makes life easier otherwise
- **Domain closure:** no model contains more domain elements than those named in constant symbols
 - Makes model checking feasible (but still very complex)
- **Closed world assumption:** whatever is not known to be true is assumed false

PROOF TREES



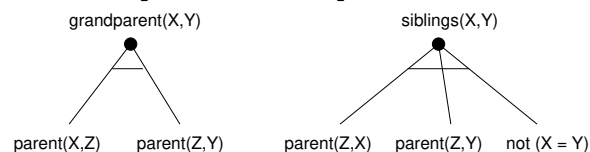
- A family tree:

```
parent(ann,bob).    parent(ann,calvin).
parent(bob,dave).   parent(dave,helen).
```



- Other family relations:

```
grandparent(X,Y) :- parent(X,Z), parent(Z,Y).
siblings(X,Y) :- parent(Z,X), parent(Z,Y), not(X = Y).
```



EXAMPLE



- FOL:

```
¬Member(a, [])
Member(a, (a, b))
Member(a, c) ⇒
Member(a, (b, c))
```

- Program (file "memb.pl"):

```
memb(A, (A, B)) .
memb(A, (B, C)) :- memb(A, C) .
... Or ...
memb(A, [A | B]) .
memb(A, [B | C]) :- memb(A, C) .
```

- Queries:

```
?- [memb].    % consult(memb) .
Yes
?- memb(X, [1, 2, 3]) .
```

X = 1

Yes

```
?- memb(X, [1, 2, 3]) .
```

X = 1 ;

X = 2 ;

X = 3 ;

No

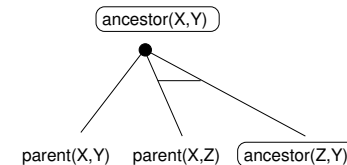
?-

PROOF TREES (CONT'D)



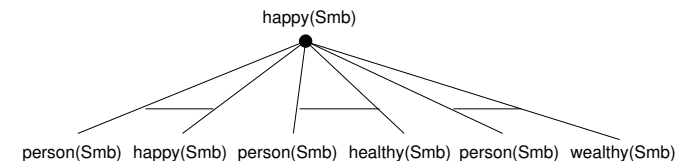
- Yet another family relation:

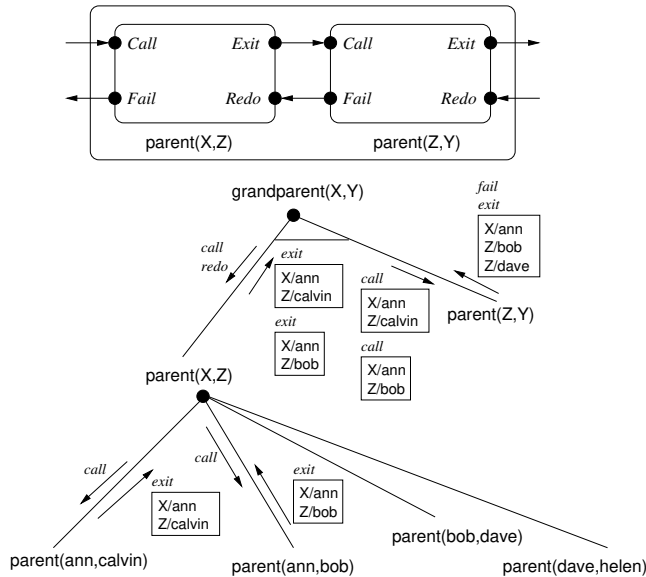
```
ancestor(X,Y) :- parent(X,Y) .
ancestor(X,Y) :- parent(X,Z), ancestor(Z,Y) .
```



- A person is happy if she is healthy, wealthy, or wise:

```
happy(Smb) :- person(Smb), happy(Smb) .
happy(Smb) :- person(Smb), healthy(Smb) .
happy(Smb) :- person(Smb), wise(Smb) .
```





- Some functions are also defined as infix operators
 - e.g., $+(1, 2)$ can be written $1+2$
- There are some functions and predicates with predefined meaning (e.g., usual relational comparison for numbers)
- Built-in predicate `is` for arithmetic
 - `?- X = 1+2.`



- Some functions are also defined as infix operators
 - e.g., $+(1, 2)$ can be written $1+2$
- There are some functions and predicates with predefined meaning (e.g., usual relational comparison for numbers)
- Built-in predicate `is` for arithmetic
 - `?- X = 1+2.`
 - `X = 1+2 ;`
 - No
 - `?- X is 1+2.`
 - `X = 3 ;`
 - No



% The board size is given by the predicate `size/1`:
`size(5).`

% The position of the knight is represented by the function
`% pos(X,Y)`. There are 8 possible moves in the middle:
`move(pos(I,J), pos(K,L)) :- K = I+1, L = J-2.`
`move(pos(I,J), pos(K,L)) :- K = I+1, L = J+2.`
`move(pos(I,J), pos(K,L)) :- K = I+2, L = J+1.`
`move(pos(I,J), pos(K,L)) :- K = I+2, L = J-1.`
`move(pos(I,J), pos(K,L)) :- K = I-1, L = J+2.`
`move(pos(I,J), pos(K,L)) :- K = I-1, L = J-2.`
`move(pos(I,J), pos(K,L)) :- K = I-2, L = J+1.`
`move(pos(I,J), pos(K,L)) :- K = I-2, L = J-1.`



```
% The board size is given by the predicate size/1:
size(5).

% The position of the knight is represented by the function
% pos(X,Y). There are 8 possible moves in the middle:
move(pos(I,J), pos(K,L)) :- K is I+1, L is J-2.
move(pos(I,J), pos(K,L)) :- K is I+1, L is J+2.
move(pos(I,J), pos(K,L)) :- K is I+2, L is J+1.
move(pos(I,J), pos(K,L)) :- K is I+2, L is J-1.
move(pos(I,J), pos(K,L)) :- K is I-1, L is J+2.
move(pos(I,J), pos(K,L)) :- K is I-1, L is J-2.
move(pos(I,J), pos(K,L)) :- K is I-2, L is J+1.
move(pos(I,J), pos(K,L)) :- K is I-2, L is J-1.

% However, if the knight is somewhere close to board's margins,
% some moves might fall out of the board:
inside(pos(A,B)) :- size(Max), A > 0, A <= Max, B > 0, B <= Max.

search1(A,A, []).
search1(A,B, [X|Mvs]) :- move(A,X), inside(X), search1(X,B,Mvs).
```



```
?- [knights].
% knights compiled 0.00 sec, 336 bytes

Yes
?- search1(pos(0,0),pos(1,2),M).

M = [pos(1, 2)] ;

ERROR: Out of local stack
Exception: (16,218) move(pos(5, 2), _G116577) ? abort
% Execution Aborted
?-
```



```
?- [knights].
% knights compiled 0.00 sec, 336 bytes

Yes
?- search1(pos(0,0),pos(1,2),M).

M = [pos(1, 2)]
```



```
search(A,B,R) :- search_aux(A,B,[A],R).

search_aux(Z,Z,L,R) :- reverse(L,R).
search_aux(X,Y,L,R) :- move(X,Z), inside(Z),
                        \+ member(Z,L),
                        search_aux(Z,Y,[Z|L],R).
```

...and then:

```
?- search(pos(0,0),pos(1,2),M).

M = [pos(0, 0), pos(1, 2)] ;

M = [pos(0, 0), pos(2, 1), pos(3, 3), pos(4, 1), |...] ;

M = [pos(0, 0), pos(2, 1), pos(3, 3), pos(4, 1), |...] ;
```

...and so on (about 127 solutions!)



Map colouring:

```
% problem instance
border(a,b).    border(a,c).    border(d,e).    border(b,e).
border(a,d).    border(b,c).    border(e,c).    border(d,c).

adj(X,Y) :- border(X,Y).
adj(X,Y) :- border(Y,X).

colour(X) :- member(X,[red,green,blue]).

colour_map([],Colouring,Colouring).
colour_map([Country|Countries], Colouring, R) :-
    colour(X), \+ conflict(Country,X,Colouring),
    colour_map(Countries,[colour(X,Country)|Colouring],R).

% violates constraint?
conflict(Country,X,Colouring) :-
    adj(Country,Country1), % more efficient if adj/2 is first
    member(colour(X,Country1),Colouring).
```

NEGATION IN CASE SELECTIONS



```
positive(X) :- X > 0.
negative(X) :- X < 0.

sign(X,+) :- positive(X).
sign(X,-) :- negative(X).
sign(X,0).
```

```
?- sign(1,X).

X = + ;
```

NEGATION AS FAILURE



- Negation in Prolog: `not/1` or `\+/1`
- Recall that Prolog assumes the **closed world paradigm**; the negation is therefore different from logical negation:

```
?- member(X,[1,2,3]).
X = 1 ;
X = 2 ;
X = 3 ;
No
```

```
?- not(member(X,[1,2,3])).
No
```

```
?- not(not(member(X,[1,2,3]))).
X = _G332 ;
No
```

- `not/1` **fails upon resatisfaction** (a goal can fail in only one way)
- `not/1` **does not** bind variables

NEGATION IN CASE SELECTIONS



```
positive(X) :- X > 0.
negative(X) :- X < 0.

sign(X,+) :- positive(X).
sign(X,-) :- negative(X).
sign(X,0).
```

```
?- sign(1,X).

X = + ;
X = 0 ;
No
```

```
sign1(X,+) :- positive(X).
sign1(X,-) :- negative(X).
sign1(X,0) :- not(positive(X)),
               not(negative(X)).
```

```
?- sign1(1,X).

X = + ;
No
```



The `!/0` predicate (pronounced “cut”) does not allow backtracking over it. All attempts to redo goals to the left of the cut fail.

- **Commit:**

```
sign2(X,+) :- positive(X), !.
sign2(X,-) :- negative(X), !.
sign2(X,0).
```

- **Succeed once:**

```
member(X, [X|_]) .
member(X, [_|Y]) :- member(X, Y) .

membchk(X, [X|_]) :- !.
membchk(X, [_|Y]) :- membchk(X, Y) .
```



- Consider the following knowledge base:

```
location(egg, duck_pen) .
location(ducks, duck_pen) .
location(fox, woods) .
location(you, house) .

connect(yard, house) .
connect(yard, woods) .

is_closed(gate) .
connect(duck_pen, yard) :- is_open(gate) .
```

- We want to move around, be able to open and close the gate, pick the egg, and so on
- In order to do this we need to modify the knowledge base dynamically



- Succeed once (cont'd):

```
fact1(1,1) .
fact1(N,R) :- N1 is N-1, fact1(N1,R1), R is N*R1.

fact2(1,1) .
fact2(N,R) :- N>1, N1 is N-1, fact2(N1,R1), R is N*R1.

fact3(1,1) :- !.
fact3(N,R) :- N1 is N-1, fact3(N1,R1), R is N*R1.
```

- Fail goal now

- An apparently useless predicate: `fail/0` always fails

```
not(P) :- P, !, fail.
not(P) .
```

- Another useful predicate: `call/1`.

- `call(P)` behaves as if `P` were passed as a goal to the interpreter

```
not(P) :- call(P), !, fail.
not(P) .
```



- Adding a fact to the knowledge base:

- `assert` adds the fact given as argument **somewhere** (implementation dependent)
- `asserta` adds the fact given as argument **at the beginning** of the knowledge base
- `assertz` adds the fact given as argument **at the end**
- all variants succeed only once

- Removing a fact from the knowledge base:

- `retract` removes one instance that unifies with the argument
- removes one more instance at each redo attempt
- fails when no removal is possible

CONVINCING THE KNOWLEDGE BASE TO ALLOW CHANGES



- All the industrial grade PROLOG implementations compile the knowledge base as to increase the speed of retrieving facts from it
 - SWI PROLOG is one such an example
- In these variants, you need to specify which facts are changeable at run time
 - These predicates will be stored separately, in an un-optimized fashion
 - The `dynamic` declaration must precede the predicate definition

```
:- dynamic(you_have/1),
   dynamic(location/2),
   dynamic(is_closed/1),
   dynamic(is_open/1).
```

ADVENTURE GAME (CONT'D)



- Opening the gate:

```
open(gate) :-
    location(you,yard),
    is_closed(gate),
    retract(is_closed(gate)),
    assert(is_open(gate)),
    write(' Opened. '), nl.

open(X) :- write(' You cannot open that '), nl.
```

- How the other creatures react:

```
ducks :-
    is_opened(gate),
    retract(location(ducks,duck_pen)),
    assert(location(ducks,yard)).

ducks.

fox :-
    location(ducks,yard),
    location(you,house),
    write(' The fox has taken a duck '), nl.

fox.
```

ADVENTURE GAME (CONT'D)



- Moving around:

```
goto(X) :-
    location(you,L),
    (connect(L,X); connect(X,L)),
    retract(location(you,L)),
    assert(location(you,X)),
    write(' You are in the '),
    write(X), nl.

goto(X) :- write(' You cannot get there '), nl.
```

- Picking up the egg:

```
pick(egg) :-
    location(you,duck_pen),
    not you_have(egg),
    assert(you_have(egg)),
    write(' You picked the egg '), nl.

pick(X) :- write(' There is nothing to pick '), nl.
```

ADVENTURE GAME (CONT'D)



- The main loop:

```
go :- done.
go :-
    write('>>'),
    read(X),
    call(X),
    go.

done :-
    location(you,house),
    you_have(egg),
    ducks, fox,
    write(' Thanks for getting the egg. '), nl.
```



```
?- go.  
>>goto(yard).  
  You are in the yard  
>>goto(duck_pen).  
  You cannot get there from here  
>>pick(egg).  
  There is nothing to pick  
>>open(gate).  
  Opened.  
>>goto(duck_pen).  
  You are in the duck_pen  
>>pick(egg).  
  You picked the egg  
>>goto(house).  
  You cannot get there from here  
>>goto(yard).  
  You are in the yard  
>>goto(house).  
  You are in the house  
  The fox has taken a duck  
  Thanks for getting the egg.  
yes
```