

CS 316: Probabilistic reasoning systems

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INDEPENDENCE

- **Absolute independence:**
 - Inference from joint distributions: huge space (and thus time) complexity, **but**
 - Two random variables A B are (absolutely) independent iff $P(A|B) = P(A)$, i.e., $P(A, B) = P(A|B)P(B) = P(A)P(B)$, **and**
 - If n Boolean variables are independent, the full joint is $\mathbb{P}(X_1, \dots, X_n) = \prod_i \mathbb{P}(X_i)$, i.e., can be specified by just n numbers; **but**
 - Absolute independence is a very strong requirement, rarely met
- **Relative independence:**
 - If I have a cavity, the probability that the probe catches does not depend on whether I have a toothache:

$$P(\text{Catch}|\text{Toothache}, \text{Cavity}) = P(\text{Catch}|\text{Cavity})$$

i.e., *Catch* is **conditionally independent** of *Toothache* given *Cavity*

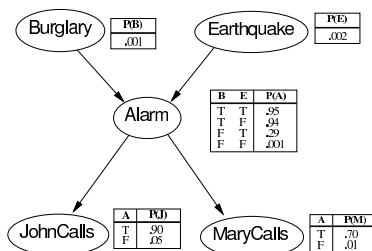
- The same independence holds if I haven't got a cavity:

$$P(\text{Catch}|\text{Toothache}, \neg\text{Cavity}) = P(\text{Catch}|\neg\text{Cavity})$$

BELIEF NETWORKS

- A simple, graphical notation for conditional independence assertions and hence for compact specification of full joint distributions
 - A set of nodes, one per variable
 - A directed, acyclic graph (of “direct influences”)
 - A conditional distribution for each node given its parents: $\mathbb{P}(X_i|\text{Parents}(X_i))$
 - In the simplest case, conditional distribution represented as a **conditional probability table**

I'm at work, neighbor John calls to say my alarm is ringing, but neighbor Mary doesn't call. Sometimes the alarm is set off by minor earthquakes. Is there a burglar?



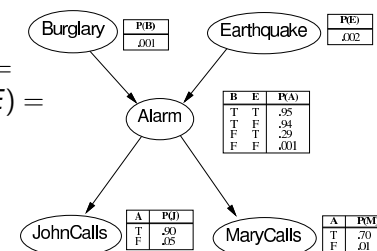
BELIEF NETWORKS (CONT'D)

- A belief network provides a complete description of the domain; if X_j is not a parent of X_i then they are conditionally independent, thus:

$$\mathbb{P}(X_i|X_1, \dots, X_{i-1}) = \mathbb{P}(X_i|\text{Parents}(X_i))$$

- More compact than a matrix, so we solve the space problem
- Computing probabilities:

$$P(J \wedge M \wedge A \wedge \neg B \wedge \neg E) = P(J|A)P(M|A)P(A|\neg B, \neg E)P(\neg B)P(\neg E) = 0.90 \times 0.70 \times 0.001 \times 0.999 \times 0.998$$





- A belief network is a correct representation of the domain only if each node is **conditionally independent of its predecessors (in node ordering), given its parents**

- e.g., the fact that Mary calls certainly depends on whether there is a burglary, but is not **directly** influenced by it (influenced only by the alarm sounding or not)

$$\mathbb{P}(M|J, A, E, B) = \mathbb{P}(M|A)$$

in general,

$$\mathbb{P}(X_i|X_1, \dots, X_{i-1}) = \mathbb{P}(X_i|Parents(X_i))$$

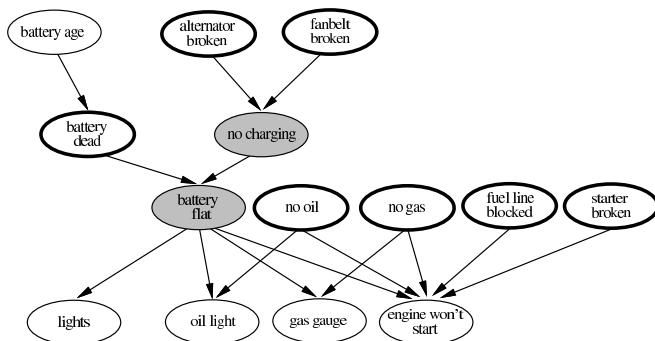
- Incremental construction:

- Choose the set of variables \mathbf{X} that describes the domain
- Choose an ordering $\langle X_1, X_2, \dots, X_n \rangle$ for \mathbf{X}
- For i from 1 to n do
 - Add a node for X_i to the network
 - Choose as parents for this node some minimal set of nodes such that it holds that $\mathbb{P}(X_i|X_1, \dots, X_{i-1}) = \mathbb{P}(X_i|Parents(X_i))$

HIDDEN VARIABLES



- Initial evidence: engine won't start
- Testable variables (thin ovals)
- Diagnosis variables (thick ovals)
- Hidden variables (shaded) ensure sparse structure, reduce parameters



- The node ordering does matter

- Compare the orderings

B, E, A, J, M	original construction
M, J, A, B, E	two more edges
M, J, E, B, A	same complexity as the full joint distribution!!

- All the above networks represent the same joint distribution, one better than the others
- The correct order of nodes is to consider the "root causes" first, then the variables they influence directly, and so on

EXACT INFERENCE IN BELIEF NETWORKS



- Simple queries: compute posterior marginal $\mathbb{P}(X_i|\mathbf{E} = \mathbf{e})$
 - e.g., $P(\text{NoGas}|\text{Gauge} = \text{empty}, \text{Lights} = \text{on}, \text{Starts} = \text{false})$
- Inference by enumeration: rewrite full joint entries using products of entries in the node tables

- Simple query on the burglary network:

$$\begin{aligned} \mathbb{P}(B|J = \text{true}, M = \text{true}) &= \mathbb{P}(B, J = \text{true}, M = \text{true}) / \mathbb{P}(J = \text{true}, M = \text{true}) \\ &= \alpha \mathbb{P}(B, J = \text{true}, M = \text{true}) \\ &= \alpha \sum_e \sum_a \mathbb{P}(B, e, a, J = \text{true}, M = \text{true}) \end{aligned}$$

- Rewrite full joint entries using product of CPT entries:

$$\begin{aligned} P(B|J = \text{true}, M = \text{true}) &= \alpha \sum_e \sum_a P(B = \text{true}) P(e) P(a|B = \text{true}, e) P(J = \text{true}|a) P(M = \text{true}|a) \\ &= \alpha P(B = \text{true}) \sum_e P(e) \sum_a P(a|B = \text{true}, e) P(J = \text{true}|a) P(M = \text{true}|a) \end{aligned}$$



ENUMERATIONASK(X, e, bn) **returns** a distribution over X
inputs: X , the query variable
 e , evidence specified as an event
 bn , a belief network specifying joint distribution $\mathbb{P}(X_1, \dots, X_n)$
 $Q(X) \leftarrow$ a distribution over X

for each value x_i of X **do**
 extend e with value x_i for X
 $Q(x_i) \leftarrow$ ENUMERATEALL(VARS[bn], e)
return NORMALIZE($Q(X)$)

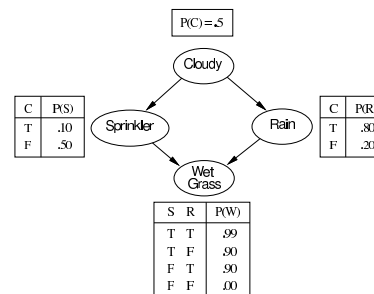
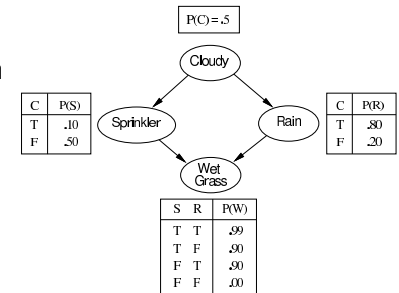
ENUMERATEALL($vars, e$) **returns** a real number
if EMPTY?($vars$) **then return** 1.0
else do
 $Y \leftarrow$ FIRST($vars$)
if Y has value y in e
then return $P(y|Parents(Y)) \times$ ENUMERATEALL(REST($vars$), e)
else return $\sum_y P(y|Parents(Y)) \times$ ENUMERATEALL(REST($vars$), e_y)
 where e_y is e extended with $Y = y$



- Variable elimination is simple and efficient
- It can be however less efficient than possible in multiply connected networks (repeat computations)
- Improvement: **clustering**
 - Basic idea: join individual nodes so that the network becomes a polytree
 - Example: two nodes with boolean variables are replaced by a “meganode” with one variable that can take the values tt, tf, ft, ff .



- For **polytrees** (at most one path between any two nodes): linear in the size of the network
- For **multiply connected networks** (dags): exponential
 - Special case: inference in propositional logic
 - So exact inference is NP-hard



- Sprinkler + Rain:**

C	$P(S + R)$			
	tt	tf	ft	ff
t	.08	.02	.72	.18
f	.10	.40	.10	.40

- Wet grass:**

$S + R$		$P(W)$
tt	tt	.99
tf	tf	.90
ft	ft	.90
ff	ff	.00

- Meganodes can have shared variables
- A special purpose inference algorithm is needed
 - Takes a form similar to constraint propagation
 - Linear time (with careful bookkeeping)
 - Still an NP-hard problem though