

# CS 515: Stable Failures Semantics

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Winter 2019

## STABLE FAILURES



- While safety properties (“something bad will never happen”) can be expressed with traces, traces cannot express **liveness properties**
  - A liveness property guarantees a certain behaviour (“something good will happen”)
  - Specifies what a process is prepared to do
- A **stable process** is a process  $P$  that can make no internal progress:  $P \downarrow = \neg(P \xrightarrow{\tau})$  (we also say that  $P$  **converges**)
  - Contrast in passing with a **divergent process**:  
 $P \uparrow = \exists (P_i)_{i \in \mathbb{N}} : P = P_0 \wedge \forall i \in \mathbb{N} : P_i \xrightarrow{\tau} P_{i+1}$
- A process **refuses** a set of actions  $X$  whenever no action from  $X$  is available from  $P$ :  $P \text{ ref } X$  iff  $\exists P' : P \xrightarrow{\diamond} P' \wedge P' \downarrow \wedge \forall a \in X : \neg(P' \xrightarrow{a})$
- The fact that a process does not refuse an event is recorded in a trace information (as before)
- In all a **stable failure** of process  $P$  is an observation  $(tr, X)$  such that  $P \xrightarrow{tr} P' \wedge P' \downarrow \wedge P' \text{ ref } X$

## SEMANTICS OF STABLE FAILURES



- The semantic model of stable failures is less abstract than traces
  - The approach to specification and verification is however the same
- Six **consistency conditions** for some  $T$  and  $SF$  sets of traces and stable failures corresponding to the same process, respectively:
  - 1  $\langle \rangle \in T \Rightarrow$  from trace semantics
  - 2  $tr_1 \leq tr_2 \wedge tr_2 \in T \Rightarrow tr_1 \in T \Rightarrow$  closure under prefix, from trace semantics
  - 3  $(tr, X) \in SF \Rightarrow tr \in T \Rightarrow$  first component of a stable failure is a trace (of the same process)
  - 4  $(tr, X) \in SF \wedge X' \subseteq X \Rightarrow (tr, X') \in SF \Rightarrow$  any subset of a refused set is also refused
  - 5  $(tr, X) \in SF \wedge \forall a \in X' : tr \frown \langle a \rangle \notin T \Rightarrow (tr, X \cup X') \in SF \Rightarrow$  a process can either perform an action or refuse it (never both)
  - 6  $\forall X \subseteq \Sigma : tr \frown \langle \checkmark \rangle \in T \Rightarrow (tr \frown \langle \checkmark \rangle, X) \in SF \Rightarrow$  a terminated process refuses anything

## PROCESS SEMANTICS



$SF[P]$  denotes the stable failures of process  $P$

- $SF[STOP] = \{(\langle \rangle, X) : X \subseteq \Sigma^\checkmark\}$
- $SF[a \rightarrow P] = \{(\langle \rangle, X) : a \notin X\} \cup \{(\langle a \rangle \frown tr, X) : (tr, X) \in SF[P]\}$
- $SF[X : A \rightarrow P] = \{(\langle \rangle, X) : A \cap X \neq \{\}\} \cup \{(\langle a \rangle \frown tr, X) : a \in A \wedge (tr, X) \in SF[P]\}$
- $SF[SKIP] = \{(\langle \rangle, X) : \checkmark \notin X\} \cup \{(\langle \checkmark \rangle, X) : X \subseteq \Sigma^\checkmark\}$
- $\text{traces}(DIV) = \{\langle \rangle\}$ ,  $SF[DIV] = \{\}$
- $\text{traces}(CHAOS) = TRACE$ ,  $SF[CHAOS] = TRACE \times 2^{\Sigma^\checkmark}$ 
  - $\text{traces}(CHAOS_A) = \{tr : \sigma(tr) \subseteq A\}$ ,  $SF[CHAOS_A] = \{(tr, X) : \sigma(tr) \subseteq A\}$
- $SF[RUN] = \{(tr, X) : X = \{\} \vee \checkmark \in \sigma(tr)\}$ 
  - $SF[RUN_A] = \{(tr, X) : \sigma(tr) \subseteq A \wedge (X \cap A = \{\} \vee \checkmark \in \sigma(tr))\}$
- $SF[P \square Q] = \{(\langle \rangle, X) : (\langle \rangle, X) \in SF[P] \cap SF[Q]\} \cup \{(tr, X) : tr \neq \langle \rangle \wedge (tr, X) \in SF[P] \cup SF[Q]\}$ 
  - Idempotence, associativity, commutativity continue to hold
  - $STOP$  continues to be a unit, but the zero is now  $RUN \square DIV$ :

$$P \square (RUN \square DIV) =_{SF} RUN \square DIV \quad (\square_{SF}\text{-zero})$$



- $\mathcal{SF}[P \sqcap Q] = \mathcal{SF}[P] \cup \mathcal{SF}[Q]$   

$$P \sqcap (Q \sqcap R) =_{SF} (P \sqcap Q) \sqcap (P \sqcap R) \quad (\sqcap - \sqcap - \text{dist})$$
- $\mathcal{SF}[P \parallel_B Q] = \{(tr, X) : \exists X_P, X_Q \in 2^{\Sigma^\vee} : X \cap (A \cup B)^\vee = (X_P \cap A^\vee) \cup (X_Q \cap B^\vee) \wedge (tr \upharpoonright A, X_P) \in \mathcal{SF}[P] \wedge (tr \upharpoonright B^\vee, X_Q) \in \mathcal{SF}[Q] \wedge \sigma(tr) \subseteq (A \cup B)^\vee\}$ 
  - All laws from the trace semantics hold, except  $\parallel$ -idem
- $\mathcal{SF}[P \parallel\parallel Q] = \{(tr, X_P \cup X_Q) : \exists tr_P, tr_Q : tr \text{ interleaves } tr_P, tr_Q \wedge X_P \upharpoonright \Sigma = X_Q \upharpoonright \Sigma \wedge (tr_P, X_P) \in \mathcal{SF}[P] \wedge (tr_Q, X_Q) \in \mathcal{SF}[Q]\}$ 
  - All laws from the trace semantics continue to apply, except  $\parallel\parallel$ -zero which becomes:  

$$P \parallel\parallel (RUN_\Sigma \parallel\parallel DIV) =_{SF} RUN_\Sigma \parallel\parallel DIV \quad (\parallel\parallel_{SF}\text{-zero})$$
- $\mathcal{SF}[P \setminus A] = \{(tr \setminus A, X) : (tr, X \cup A) \in \mathcal{SF}[P]\}$
- $\mathcal{SF}[f(P)] = \{(f(tr), X) : (tr, f^{-1}(X)) \in \mathcal{SF}[P]\}$
- $\mathcal{SF}[f^{-1}(P)] = \{(tr, X) : (f(tr), f(X)) \in \mathcal{SF}[P]\}$



- $\mathcal{SF}[P; Q] = \{(tr, X) : (tr, X \cup \{\checkmark\}) \in \mathcal{SF}[P]\} \cup \{(tr_1 \widehat{\ } tr_2, X) : tr_1 \langle \checkmark \rangle \in \text{traces}(P) \wedge (tr_2, X) \in \mathcal{SF}[Q]\}$
- $\mathcal{SF}[P \triangle Q] = \{(tr, X) : (tr, X) \in \mathcal{SF}[P] \wedge (\checkmark \in \sigma(tr) \vee (\langle \rangle, X) \in \mathcal{SF}[Q])\} \cup \{(tr_1 \widehat{\ } tr_2, X) : tr_1 \in \text{traces} P \wedge \checkmark \notin \sigma(tr_1) \wedge (tr_2, X) \in \mathcal{SF}[Q] \wedge tr_2 \neq \langle \rangle\}$
- **Recursion** needs a different SOS rule for the stable failure model to make unguarded expressions unstable:

$$\frac{}{N \xrightarrow{\tau} P} [N = P]$$

- The minimal process for stable failures is *DIV*, and so

$$\mathcal{SF}[N = F(N)] = \bigcup_{n \in \mathbb{N}} \mathcal{SF}[F^n(DIV)]$$

- The laws of recursion unwinding and unique fixed points continue to hold

$$F(Y) \text{ guarded} \wedge (F(P_1) =_{SF} P_1) \wedge (F(P_2) =_{SF} P_2) \implies P_1 =_{SF} P_2 \quad (\text{UFP}_{SF})$$