

Practical aspects of server design

Stefan D. Bruda

CS 464/564, Fall 2023



- A (Unix) server is different from a normal program
 - In particular, a server does not interact with a user
 - It communicates instead with other programs over a network
 - It also spawns threads/processes (which are not under immediate user control)
- One is faced thus with a bunch of new issues, including
 - Preventing users to affect server's execution in other ways than the ones specified
 - Providing a mechanism for the server to report status and errors
 - Resource management
 - Access control and other security issues



- A normal program runs in **foreground**
 - It is attached to a **terminal** (more general, a “tty”)
 - It receives user **input** from that terminal
 - It prints **output** (using `cout<<`, `printf`, ...) and **error messages** (using `cerr<<`, `perror`, ...) to the same terminal
- A server is a **daemon** i.e., it runs in **background**
 - A production server is not attached to any terminal
 - Instead, it is launched upon boot, maybe even before terminals are born
 - Thus, it does not accept user input
 - It must send the output to something else than a terminal too



- The easy way: you put the server in background explicitly

```
shfd -d -v &
```

- The hard way: the server puts itself into the background
 - You start with a process that does the server initialization
 - It prints whatever messages it wants (to the terminal or something)
 - It then goes in the background for the rest of the job

```
int main (...) {  
    Initialize server (socket binding, preparation of the file system)  
    int bgp_id = fork();  
    if (bgp_id < 0) {  
        perror("startup fork");  
        return 1;    }  
    if (bgp_id)      // parent dies  
        return 0;  
    Child continues and becomes the server  
}
```



OK, but why?

- A server is usually started up by the **init script**
- This script starts the servers in a specific order
 - E.g., the database server should be started before the Web server (which needs it)
- The init script cannot put everything into the background from the very start
 - It has to make sure that the server actually started before moving forward
- On the other hand, if the server never gets into background, the init script never gets a chance to go ahead and start the other services
- Ergo, a server that expects to be launched by the init script (they all should!)
 - Sits in foreground until it makes sure that the startup succeeded
 - Goes then into background for the actual work



DEBUGGING A DAEMON

- A server will eventually need debugging, like any other program
- When this happens, it is much more convenient to run the server in foreground
 - So that we can see the output and maybe stop it by typing `Control-c`
- So it is convenient to have a **command line switch** that will keep the server in foreground:

```
int main (...) {  
    Initialize (socket binding, preparation of the file system)  
    if ( strcmp(argv[1],"-d") == 0 ) {  
        argc--; argv++;  
        int bgpid = fork();  
        if (bgpid < 0) {  
            perror("startup fork");  
            return 1;    }  
        if (bgpid)  
            return 0;  
    }  
    Child (or parent) continues with the server code  
}
```

- Normal operation:
`shfd -f 10000`
- Debug:
`shfd -d -f 10000`



- Debugging programs is generally difficult
- Debugging servers is even more so (they are concurrent, grumpy, etc.)
- Typical debugging involves verbose logging
- In the process the server usually stays attached so that we can stop (and restart it) as needed
- While attached, it is probably a good idea **not** to redirect the standard output and standard error streams, as it is often more convenient to have the whole output in the terminal
- These variations in behaviour are best accomplished via **command-line switches**



- Normal way to obtain the command line arguments:

```
#include <stdio.h>
#include <unistd.h>
```

```
int main (int argc, char** argv) {
```

```
    for (int i = 1; i < argc; i++) {
        printf("argv[%d] = %s\n", i, argv[i]);    }    }
```



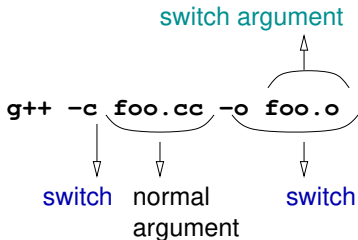

- Obtain command line arguments by identifying switches:

```
#include <stdio.h>
#include <unistd.h>

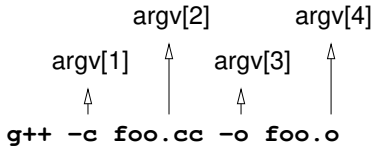
extern char *optarg;
extern int optind;

int main (int argc, char** argv) {
    int c;
    printf("----- options: -----\n");
    while ((c = getopt (argc,argv,"abcd:")) != -1) {
        printf("opt: %c arg %s\n", (char)c, optarg);
    }
    argc -= optind - 1; argv += optind - 1;
    printf("----- remaining args: -----\n");
    for (int i = 1; i < argc; i++) {
        printf("argv[%d] = %s\n", i, argv[i]); } }
```

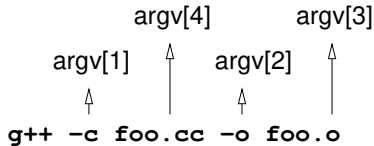
COMMAND-LINE SWITCHES FOR VERBOSE OUTPUT



Before parsing options:



After parsing options:





- **-d** or **-D** usually stand for “debug”
 - This might make the daemon more verbose but it almost always prevents the daemon from detaching
 - Typically output is produced to standard output (as opposed to log facilities), but this is not always the case (probable cause: laziness)
- **-v** usually stands for “verbose output”
 - It increases the verbosity of the program but does not necessarily keep the program attached and does not necessarily change the destination of program’s output
 - Often different levels of verbosity are needed; this is accomplished typically by providing multiple **-v** switches in the command line (the more occurrences of **-v** the more verbose the program)
- As an alternative to the command line debugging behaviour can be changed via configuration options in a configuration file
 - Often both methods are supported



- We have first to find the process id of the server process

- We do `ps aux`, we get a lot of lines like this

```
USER  PID  %CPU %MEM  VSZ  RSS TTY      STAT START TIME COMMAND
...
bruda 13319 0.0  0.1  2572  816 pts/1  S    12:15 0:00 shfd -d -D
...
```

and then we hunt for our server between them

- We do `ps aux | grep name`, we get only the lines that contain **name**
 - We already have the pid (useful!) — how?
- We could then send a signal to the server

<code>kill pid</code>	sends SIGQUIT to pid	(which may terminate)
<code>kill -KILL pid</code>	sends SIGKILL to pid	(which will terminate)
<code>kill -HUP pid</code>	sends SIGHUP to pid	(which restarts if civilized)



- Servers are lonely. It does not make sense to run multiple copies of a server on the same machine
 - How do we prevent multiple copies to run?



- Servers are lonely. It does not make sense to run multiple copies of a server on the same machine
 - How do we prevent multiple copies to run?
- Each server has a well-known associated **lock file**
 - Different servers use different lock files, but a server will always use the same lock file
- Immediately upon startup the server tries to acquire a lock on this file
 - If it succeeds, it goes ahead with the rest
 - If it fails, it terminates (there is another copy running)
 - An error message would be nice too. . .
 - When the server exits, it releases the lock on the file and deletes the file
 - Loosely speaking, each server runs in a critical region



- Servers are lonely. It does not make sense to run multiple copies of a server on the same machine
 - How do we prevent multiple copies to run?
- Each server has a well-known associated **lock file**
 - Different servers use different lock files, but a server will always use the same lock file
- Immediately upon startup the server tries to acquire a lock on this file
 - If it succeeds, it goes ahead with the rest
 - If it fails, it terminates (there is another copy running)
 - An error message would be nice too. . .
 - When the server exits, it releases the lock on the file and deletes the file
 - Loosely speaking, each server runs in a critical region
- The lock file is also a good place to hold the **process id of the server**



- Except for the signals they like, daemons do not want to talk to you
- If you leave them in the state typical for a normal program, they might even get angry and refuse to do the work
 - This happens when they try for some reason to access standard input (descriptor 0)
 - So we have to **close** descriptor 0
 - What the heck, we close **all** the descriptors except standard output and standard error!

```
for (int i = 0; i < getdtablesize(); i++)  
    if (i != 1 && i != 2)  
        close(i);
```

- Closing descriptors is very important, **we thus prevent the server from consuming resources unnecessarily** but most importantly **we have control over the descriptors** (a matter of security)
- But note that we close them **before opening back those descriptors we actually need** (so that we positively know what are the files on which the server operates)
- Closing descriptor 0 does not make our server happy though (**why?**)



- The server may still try to access descriptor 0
 - Many library functions assume that the first three descriptors are open
 - We just exchange one error for another!
- So we open descriptor 0 again
 - This time, descriptor 0 will point to a special device which does nothing (“bit bucket”)
 - This device is called, suggestively, `/dev/null`
 - Reading from `/dev/null` always return an end of file
 - Anything written to `/dev/null` is discarded

```
for (int i = 0; i < getdtablesize(); i++)
    if (i != 1 && i != 2)
        close(i);
```

```
// We closed descriptor 0 already, so this
// will be the first one available
int fd = open("/dev/null", O_RDWR);
```



- Each Unix process inherits a connection to its **controlling tty**
 - A user that started a process can control it by issuing appropriate control commands to that process' controlling tty
- Unlike normal programs, servers should not receive signals generated by the process that started it
 - Signaling from the tty to the piece of code that starts the server is acceptable (sometimes desired), signaling to the server itself is not
- A server must therefore **detach itself** from the controlling tty

```
#include <sys/ioctl.h>
```

```
int fd = open("/dev/tty",O_RDWR);  
ioctl(fd,TIOCNOTTY,0);  
close(fd);
```



- OK, so we have now no terminal, where do we put the output?



- OK, so we have now no terminal, where do we put the output?
- We **redirect** standard output (descriptor 1) and standard error (descriptor 2)
- Using the command line:

- Redirecting both to the same file:

```
shfd -d >& global-output-file  
shfd -d >>& global-output-file
```

- Redirecting to different files (bash-like shells):

```
shfd -d 1> output-file 2> error-file  
shfd -d 1>> output-file 2>> error-file
```



- Command line syntax varies
- Not a good idea security-wise to rely on descriptors opened by somebody else
- How about the initializing code? It should print to the terminal



- Command line syntax varies
- Not a good idea security-wise to rely on descriptors opened by somebody else
- How about the initializing code? It should print to the terminal
- So we redirect output from inside the program

```
// We close everything!!
for (int i = getdtablesize() - 1; i >= 0 ; i--)
    close(i);
// We closed descriptor 0 already, so this
// will be the first one available
int fd = open("/dev/null", O_RDWR);
// We now re-open descriptors 1 and 2, in this order:
```

Same file:

```
fd = open("global-output-file", O_WRONLY|O_CREAT|O_APPEND);
dup(fd);
```

Different files:

```
fd = open("output-file", O_WRONLY|O_CREAT|O_APPEND);
fd = open("error-file", O_WRONLY|O_CREAT|O_APPEND);
```



- There is no signal from the controlling tty, but nonetheless a server may receive signals (e.g., from you when you use the command `kill`)
- Some signals (e.g., `SIGHUP`, maybe) have some meaning to the server
 - One signal **always** has some meaning to any Unix program namely, `SIGKILL`
- Signals with meanings should have associated **signal handlers** (except `SIGKILL`)
`signal(signal, handler-function);`
- Some other signals do not have any meaning
 - Signals that are not needed **should be ignored**
 - There is a predefined function that does exactly this: `SIG_IGN`
`signal(signal, SIG_IGN);`



- Notable signal
- Sent to the server when a client closes the connection
- When unhandled a SIGPIPE brings down the whole process
- A server must not die when a client leaves
- Therefore this signal should **always** be explicitly handled
- Ignoring it is fine for most applications, since the socket **also** receives an end of file



- Unix places each process in a **process group**
- It can then treat a set of related processes as one entity
- A server inherits membership in a process group
- **But** usually a server operates independently from any process group
 - E.g., it should not receive signals sent to its parent's group
 - The server must thus **leave** its parent's group:
`setpgid(what-process,to-what-group);`
 - The process id of the current process (which is passed to `setpgid`) can be obtained by using the function `getpid`
 - To create a new, private group we pass 0 as second argument of `setpgrp`. So we do:
`setpgid(getpid(),0);`



- Servers may run with **root privileges**
 - In other words, they can do whatever they please with your system
 - So **you the programmer** have to make sure they do not do things that interfere with normal system operation
- Careful programming is one way of keeping them at bay
 - In particular, it is crucial that you check for array bounds, and that you do not access memory areas you do not own
 - Not checking for these is the most usual cause for issuing security updates (and for people cracking into your system)
 - Obviously a complex problem (to be continued)
- In addition, you should be careful about what servers write to disk and where

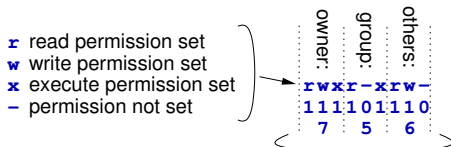


DAEMONS AND THEIR DIRECTORIES

- When a program is launched, it inherits an environment variable called the **current working directory**
- When a program creates or opens a file it looks in this current working directory
- Servers are launched by the init script, which works in a directory whose content should not be modified
- Servers have this habit to write on disk
- You can specify the directory they write into by providing absolute paths to your files
- **But** a server that encounters an error condition might **dump core** (write to disk a memory image for debugging purposes. . . in the current working directory!)
- **But** a server started by the system administrator will have the current directory as the home directory of the administrator
- **But** a server working in some directory will prevent that directory to be unmounted even if the server does not use the directory for anything
- **Conclusion:** You should move a server to a **known, "safe" directory**. Most servers do: `chdir("/run/shfd");`



- Some data that is written to files is log data, which should be readable (but not writable) by many people
- Some other data should not be accessible to anybody else (e.g., passwords)
- Each file in a Unix file system has a set of permissions to control access to files
 - You can (and should) specify at creation time the permissions of the file you create
 - You can also specify a set of permissions that will never be set (the **umask**)



permissions for the file (declared):	756	
umask (denied permissions):	037	Bitwise AND with
<hr/>		the negated umask
actual permissions for the file:	740	



- You do not want to run into the possibility of creating a file owned by the administrator and with all the permissions set (777). Not even by chance!
- So, besides setting suitable permissions for each file you create, it is a very good idea to provide a suitable umask for the server as a whole
- To set a (new) umask, you use the system call `umask`
 - It is very comfortable to work with numbers in **octal** when you deal with file permissions
 - This way a digit corresponds with a set of permissions for a given group of users
 - In C/C++ a literal integer whose first digit is 0 is considered to be in base 8
 - So when you call `umask`, it is likely that you do not want to write

```
umask(137);
```

but rather

```
umask(0137);
```
- Always keep in mind that the umask specifies permissions that are **denied**



- If the main server exits, no problems will arise
- However, if the server process creates other processes, you may end up with **zombie processes**
 - So remember to always wait after your children (as we talked about earlier)
 - That is, if your server spawns new processes, it has to have a suitable handler for the SIGCHLD signal
- Same issue is applicable to **attached threads** that are not joined