# CS 467/567: NP-complete problems

Stefan D. Bruda

Winter 2023



- Abstract problem: relation Q over the set I of problem instances and the set S of problem solutions: Q ⊆ I × S
  - Complexity theory deals with decision problems or languages ( $S = \{0, 1\}$ )
    - Technically a language is a set of strings
    - A problem  $Q \subseteq I \times \{0, 1\}$  ca be rewritten as the language (set)  $L(Q) = \{w \in I : (w, 1) \in Q\}$
  - Many abstract problems are optimization problems instead; however, we can
    usually restate an optimization problem as a decision problem which require
    the same amount of resources to solve

- Abstract problem: relation Q over the set I of problem instances and the set S of problem solutions: Q ⊆ I × S
  - Complexity theory deals with decision problems or languages ( $S = \{0, 1\}$ )
    - Technically a language is a set of strings
    - A problem  $Q \subseteq I \times \{0, 1\}$  ca be rewritten as the language (set)  $L(Q) = \{w \in I : (w, 1) \in Q\}$
  - Many abstract problems are optimization problems instead; however, we can
    usually restate an optimization problem as a decision problem which require
    the same amount of resources to solve
- Concrete problem: an abstract decision problem with I = {0, 1}\*
  - Abstract problem mapped on concrete problem using an encoding  $e: I \rightarrow \{0, 1\}^*$
  - $Q \subseteq I \times \{0,1\}$  mapped to the concrete problem  $e(Q) \subseteq e(I) \times \{0,1\}$
  - Encodings will not affect the performance of an algorithm as long as they are polynomially related
- An algorithm solves a concrete problem in time O(T(n)) whenever the algorithm produces in O(T(n)) time a solution for any problem instance *i* with |i| = n



- Complexity theory analyzes problems from the perspective of how many resources (e.g., time, storage) are necessary to solve them
  - Given some abstract problem that requires certain resource (time) bounds to solve, it is generally easy to find a language that requires the same resource bounds to decide
  - Sometime (but not always) finding an algorithm for deciding the language immediately implies an algorithm for solving the problem

- Complexity theory analyzes problems from the perspective of how many resources (e.g., time, storage) are necessary to solve them
  - Given some abstract problem that requires certain resource (time) bounds to solve, it is generally easy to find a language that requires the same resource bounds to decide
  - Sometime (but not always) finding an algorithm for deciding the language immediately implies an algorithm for solving the problem

• Traveling salesman (TSP): Given  $n \ge 2$ , a matrix  $(d_{ii})_{1 \le i, i \le n}$  with  $d_{ii} > 0$ and  $d_{ii} = 0$ , find a permutation  $\pi$  of  $\{1, 2, ..., n\}$  such that  $c(\pi)$ , the cost of  $\pi$  is minimal, where  $c(\pi) = d_{\pi_1\pi_2} + d_{\pi_2\pi_3} + \cdots + d_{\pi_{n-1}\pi_n} + d_{\pi_n\pi_1}$ 

- TSP the language (take 1):  $\{((d_{ij})_{1 \le i,j \le n}, B) : n \ge 2, B \ge 0, \text{ there exists a}\}$ permutation  $\pi$  such that  $c(\pi) \leq B$
- TSP the language (take 2), or the Hamiltonian graphs: Exactly all the graphs that have a (Hamiltonian) cycle that goes through all the vertices exactly once
- Note in passing: A cycle that uses all the edges exactly once is Eulerian; a graph G is Eulerian iff



- There is a path between any two vertices that are not isolated, and
  - Every vertex has an in-degree equal to its out-degree

# LANGUAGES? PROBLEMS? (CONT'D)



- Clique: Given an undirected graph G = (V, E), find the maximal set  $C \subseteq V$  such that  $\forall v_i, v_j \in C : (v_i, v_j) \in E$  (*C* is a clique of *G*)
  - Clique, the language: {(G = (V, E), K) : K ≥ 2 : there exists a clique C of V such that |C| ≥ K}

# LANGUAGES? PROBLEMS? (CONT'D)



- Clique: Given an undirected graph G = (V, E), find the maximal set  $C \subseteq V$  such that  $\forall v_i, v_i \in C : (v_i, v_i) \in E$  (*C* is a clique of *G*)
  - Clique, the language: {(G = (V, E), K) : K ≥ 2 : there exists a clique C of V such that |C| ≥ K}
- SAT: Fix a set of variables  $X = \{x_1, x_2, \dots, x_n\}$  and let

$$\overline{X} = \{\overline{x_1}, \overline{x_2}, \dots, \overline{x_n}\}$$

- An element of  $X \cup \overline{X}$  is called a literal
- A formula (or set/conjunction of clauses) is  $\alpha_1 \land \alpha_2 \land \cdots \land \alpha_m$  where

 $\alpha_i = x_{a_1} \lor x_{a_2} \lor \cdots \lor x_{a_k}, 1 \leqslant i \leqslant m, \text{ and } x_{a_i} \in X \cup \overline{X}$ 

- An interpretation (or truth assignment) is a function  $I: X \to \{\top, \bot\}$
- A formula *F* is satisfiable iff there exists an interpretation under which *F* evaluates to *⊤*.
- SAT = {F : F is satisfiable }
- 2-SAT, 3-SAT are variants of SAT (with the number of literals in every clause restricted to a maximum of 2 and 3, respectively)

# LANGUAGES? PROBLEMS? (CONT'D)



- Clique: Given an undirected graph G = (V, E), find the maximal set  $C \subseteq V$  such that  $\forall v_i, v_i \in C : (v_i, v_i) \in E$  (*C* is a clique of *G*)
  - Clique, the language: {(G = (V, E), K) : K ≥ 2 : there exists a clique C of V such that |C| ≥ K}
- SAT: Fix a set of variables  $X = \{x_1, x_2, \dots, x_n\}$  and let

$$\overline{X} = \{\overline{x_1}, \overline{x_2}, \dots, \overline{x_n}\}$$

- An element of  $X \cup \overline{X}$  is called a literal
- A formula (or set/conjunction of clauses) is  $\alpha_1 \land \alpha_2 \land \cdots \land \alpha_m$  where

 $\alpha_i = x_{a_1} \lor x_{a_2} \lor \cdots \lor x_{a_k}, 1 \leqslant i \leqslant m, \text{ and } x_{a_i} \in X \cup \overline{X}$ 

- An interpretation (or truth assignment) is a function  $I: X \to \{\top, \bot\}$
- A formula *F* is satisfiable iff there exists an interpretation under which *F* evaluates to *⊤*.
- SAT = {F : F is satisfiable }
- 2-SAT, 3-SAT are variants of SAT (with the number of literals in every clause restricted to a maximum of 2 and 3, respectively)
- Note in passing: Sometimes SAT (2-SAT, 3-SAT) is called CNF (2-CNF, 3-CNF) because the input formulae are written in conjunctive normal form



- Complexity class  $\mathcal{P}$ : the class of all the concrete problems that are solvable in polynomial time
  - Meaning that for any problem in  $\mathcal{P}$  there exists an algorithm that solves it in  $O(n^k)$  time for some constant  $k \ge 0$



- Complexity class  $\mathcal{P}$ : the class of all the concrete problems that are solvable in polynomial time
  - Meaning that for any problem in  $\mathcal{P}$  there exists an algorithm that solves it in  $O(n^k)$  time for some constant  $k \ge 0$
- For some  $f : \mathbb{N} \to \mathbb{N}$ , a Turing machine  $M = (K, \Sigma, \Delta, s, \{h\})$  is *f*-time bounded iff for any  $w \in \Sigma^*$ : there is no configuration *C* such that  $(s, \#w\underline{\#}) \vdash_M^{f(|w|)+1} C$ 
  - *M* is polynomially (time) bounded iff *M* is *p*-time bounded for some polynomial  $p = O(n^k)$
  - Problem *p* is polynomially solvable iff there exists a deterministic polynomially bounded Turing machine that solves *p* ⇒ complexity class *P*
- $\mathcal{P}$  (as well as all the other complexity classes) are defined based on worst-case analysis



• Complexity class  $\mathcal{NP}$ : the class of exactly all the problems solvable by nondeterministic, polynomially bounded Turing machines



- Complexity class  $\mathcal{NP}$ : the class of exactly all the problems solvable by nondeterministic, polynomially bounded Turing machines
- Verification algorithm: An algorithm A with two inputs: an ordinary problem instance x and a certificate y
  - A verifies the input x if there exists a certificate y such that A(x, y) = 1
  - The language verified by A is  $L = \{x \in \{0, 1\}^* : \exists y \in \{0, 1\}^* : A(x, y) = 1\}$
  - A verifies L if for any string x ∈ L, there exists a certificate y that A can use to prove that x ∈ L; for any string x ∉ L there must be no certificate proving that x ∈ L
- Complexity class  $\mathcal{NP}$ : the class of all the problems verifiable in deterministic polynomial time
  - L∈ NP iff there exists a polynomial verification algorithm A and a constant c such that L = {x ∈ {0,1}\* : ∃ y ∈ {0,1}\* : |y| = O(|x|<sup>c</sup>) ∧ A(x, y) = 1}
- Complexity class  $\mathcal{EXP}$ : exactly all the problems solvable by exponentially-bounded, deterministic algorithms
  - $\mathcal{P} \subseteq \mathcal{NP} \subseteq \mathcal{EXP}$



- A problem *Q* can be reduced to another problem *Q'* if any instance of *Q* can be "easily rephrased" as an instance of *Q'* 
  - If Q reduces to Q' then Q is "not harder to solve" than Q'

# POLYNOMIAL REDUCTIONS & NP-COMPLETENESS



- A problem *Q* can be reduced to another problem *Q*' if any instance of *Q* can be "easily rephrased" as an instance of *Q*'
  - If Q reduces to Q' then Q is "not harder to solve" than Q'
- Polynomial reduction: A language L<sub>1</sub> is polynomial-time reducible to a language L<sub>2</sub> (L<sub>1</sub> ≤<sub>P</sub> L<sub>2</sub>) iff there exists a polynomial algorithm F that computes the function f: {0,1}\* → {0,1}\* such that ∀x ∈ {0,1}\* : x ∈ L<sub>1</sub> iff f(x) ∈ L<sub>2</sub>
  - Polynomial reductions show that a problem is not harder to solve than another within a polynomial-time factor

# POLYNOMIAL REDUCTIONS & NP-COMPLETENESS



- A problem *Q* can be reduced to another problem *Q*' if any instance of *Q* can be "easily rephrased" as an instance of *Q*'
  - If Q reduces to Q' then Q is "not harder to solve" than Q'
- Polynomial reduction: A language  $L_1$  is polynomial-time reducible to a language  $L_2$  ( $L_1 \leq_P L_2$ ) iff there exists a polynomial algorithm F that computes the function  $f : \{0, 1\}^* \rightarrow \{0, 1\}^*$  such that  $\forall x \in \{0, 1\}^* : x \in L_1$  iff  $f(x) \in L_2$ 
  - Polynomial reductions show that a problem is not harder to solve than another within a polynomial-time factor

#### Lemma

 $L_1 \leqslant_P L_2 \land L_2 \in P \Rightarrow L_1 \in P$ 

# POLYNOMIAL REDUCTIONS & NP-COMPLETENESS



- A problem *Q* can be reduced to another problem *Q*' if any instance of *Q* can be "easily rephrased" as an instance of *Q*'
  - If Q reduces to Q' then Q is "not harder to solve" than Q'
- Polynomial reduction: A language  $L_1$  is polynomial-time reducible to a language  $L_2$  ( $L_1 \leq_P L_2$ ) iff there exists a polynomial algorithm F that computes the function  $f : \{0, 1\}^* \rightarrow \{0, 1\}^*$  such that  $\forall x \in \{0, 1\}^* : x \in L_1$  iff  $f(x) \in L_2$ 
  - Polynomial reductions show that a problem is not harder to solve than another within a polynomial-time factor

#### Lemma

$$L_1 \leqslant_P L_2 \land L_2 \in P \Rightarrow L_1 \in P$$

- A problem *L* is NP-hard iff  $\forall L' \in \mathcal{NP} : L' \leq_P L$
- A problem *L* is NP-complete ( $L \in NPC$ ) iff *L* is NP-hard and  $L \in NP$

#### Theorem

Let L be some NP-complete problem; then  $\mathcal{P} = \mathcal{NP}$  iff  $L \in \mathcal{P}$ 



- Are there NP-complete problems at all?
  - SAT  $\in \mathcal{NPC}$  (Stephen Cook, 1971)
- The first is the hard one: need to show that every problem in NP reduces to our problem
- Then in order to find other NP-complete problems all we need to do is to find problems such that some problem already known to be NP-complete reduces to them
  - This works because polynomial reductions are closed under composition = are transitive
- Then it is apparently easy to use the theorem stated earlier:

Let *L* be some NP-complete problem; then  $\mathcal{P} = \mathcal{NP}$  iff  $L \in \mathcal{P}$ 

### BOUNDED TILING



- Tiling system:  $\mathcal{D} = (D, d_0, H, V, s)$ 
  - D is a finite set of tiles
  - $d_0 \in D$  is the initial corner tile
  - $H, V \in D \times D$  are the horizontal and vertical tiling restrictions
  - s > 0 is a constant
- Tiling:  $f : \mathbb{N}_s \times \mathbb{N}_s \to D$  such that
  - $f(0,0) = d_0$
  - $\forall 0 \le m < s, 0 \le n < s 1 : (f(m, n), f(m, n + 1)) \in V$
  - $\forall 0 \le m < s 1, 0 \le n < s : (f(m, n), f(m + 1, n)) \in H$
- The bounded tiling problem:
  - Given a tiling system  $\mathcal{D}$ , a positive integer *s* and an initial tiling  $f_0 : \mathbb{N}_s \to D$
  - Find whether there exists a tiling function *f* that extends *f*<sub>0</sub>
- Bounded tiling is in NP (why?)

### BOUNDED TILING IS NP-COMPLETE

• Need to find reductions from all problems in  $\mathcal{NP}$  to bounded tiling



### BOUNDED TILING IS NP-COMPLETE



- $\bullet\,$  Need to find reductions from all problems in  $\mathcal{NP}$  to bounded tiling
  - The only thing in common to all the  $\mathcal{NP}$  problems is that each of them is decided by a nondeterministic, polynomially bounded Turing machine
  - We therefore find a reduction from an arbitrary such a machine to bounded tiling

### BOUNDED TILING IS NP-COMPLETE



- $\bullet$  Need to find reductions from all problems in  $\mathcal{NP}$  to bounded tiling
  - The only thing in common to all the  $\mathcal{NP}$  problems is that each of them is decided by a nondeterministic, polynomially bounded Turing machine
  - We therefore find a reduction from an arbitrary such a machine to bounded tiling
- We find a tiling system such that each row in the tiling corresponds to one configuration of the given Turing machine

 $\forall (q, a, p, L) \in \Delta \land b \in \Sigma :$ 

Initial tiling:

$$\begin{array}{c}
(p,b) \\
Lp \\
b \\
\end{array}$$



### **SAT** $\in \mathcal{NP}$

- Nondeterministically guess an interpretation then check that the interpretation satisfies the formula
- Both of these take linear time

### SAT is NP-hard

- Reduction of bounded tiling to SAT
- Variables: *x<sub>nmd</sub>* standing for "tile *d* is at position (*n*, *m*) in the tiling"
- Construct clauses such that  $x_{nmd} = \top$  iff f(m, n) = d
- First specify that we have a function:
  - Each position has at least one tile:  $\forall 0 \leq m, n \leq s : x_{mnd_1} \lor x_{mnd_2} \lor \cdots$
  - No more than one tile in a given position:  $\forall 0 \le m, n \le s, d \ne d'$ :  $\overline{x_{mnd}} \lor \overline{x_{mnd'}}$
- Then specify the restrictions H and V:

• 
$$(d, d') \in D^2 \setminus H \Rightarrow \overline{x_{mnd}} \lor \overline{x_{m+1nd'}}$$
  $(d, d') \in D^2 \setminus V \Rightarrow \overline{x_{mnd}} \lor \overline{x_{mn+1d'}}$ 

• 3-SAT is also NP-complete



• 3-SAT is NP-complete



- 3-SAT is NP-complete
  - Hint: any clause  $x_1 \lor x_2 \lor \cdots \lor x_n$  is logically equivalent with  $(x_1 \lor x_2 \lor x'_2) \land (\overline{x'_2} \lor x_3 \lor x'_3) \land (\overline{x'_3} \lor x_4 \lor x'_4) \land \cdots \land (\overline{x'_{n-2}} \lor x_{n-1} \lor x_n)$
- CLIQUE = { $(G = (V, E), k) : k \ge 2$ : there exists a clique *C* of *V* with |C| = k}

Membership in  $\mathcal{NP}$  and 3-SAT  $\leq_P$  CLIQUE  $\Rightarrow$  CLIQUE  $\in \mathcal{NPC}$ 



#### • 3-SAT is NP-complete

- Hint: any clause  $x_1 \lor x_2 \lor \cdots \lor x_n$  is logically equivalent with
- $(X_1 \lor X_2 \lor X'_2) \land (\overline{X'_2} \lor X_3 \lor X'_3) \land (\overline{X'_3} \lor X_4 \lor X'_4) \land \cdots \land (\overline{X'_{n-2}} \lor X_{n-1} \lor X_n)$
- CLIQUE = { $(G = (V, E), k) : k \ge 2$  : there exists a clique *C* of *V* with |C| = k}

Membership in  $\mathcal{NP}$  and 3-SAT  $\leq_P$  CLIQUE  $\Rightarrow$  CLIQUE  $\in \mathcal{NPC}$ 

- Start from  $\phi = C_1 \wedge C_2 \wedge \cdots \wedge C_k$ , construct G = (V, E)
- Start with  $V = \emptyset$  and  $E = \emptyset$
- For each clause  $C_r = l_1^r \vee l_2^r \vee l_3^r$  add vertices  $v_1^r$ ,  $v_2^r$ , and  $v_3^r$  to V
- Add (v<sup>r</sup><sub>i</sub>, v<sup>s</sup><sub>j</sub>) to E whenever r ≠ s and l<sup>r</sup><sub>i</sub> is not the negation of l<sup>s</sup><sub>j</sub> (l<sup>r</sup><sub>i</sub> is and l<sup>s</sup><sub>j</sub> are consistent)



#### • 3-SAT is NP-complete

- Hint: any clause x<sub>1</sub> v x<sub>2</sub> v ··· x<sub>n</sub> is logically equivalent with
  - $(\mathbf{X}_{1} \lor \mathbf{X}_{2} \lor \mathbf{X}_{2}') \land (\overline{\mathbf{X}_{2}'} \lor \mathbf{X}_{3} \lor \mathbf{X}_{3}') \land (\overline{\mathbf{X}_{3}'} \lor \mathbf{X}_{4} \lor \mathbf{X}_{4}') \land \cdots \land (\overline{\mathbf{X}_{n-2}'} \lor \mathbf{X}_{n-1} \lor \mathbf{X}_{n})$
- CLIQUE = { $(G = (V, E), k) : k \ge 2$  : there exists a clique *C* of *V* with |C| = k}

Membership in  $\mathcal{NP}$  and 3-SAT  $\leq_P$  CLIQUE  $\Rightarrow$  CLIQUE  $\in \mathcal{NPC}$ 

- Start from  $\phi = C_1 \wedge C_2 \wedge \cdots \wedge C_k$ , construct G = (V, E)
- Start with  $V = \emptyset$  and  $E = \emptyset$
- For each clause  $C_r = l_1^r \vee l_2^r \vee l_3^r$  add vertices  $v_1^r$ ,  $v_2^r$ , and  $v_3^r$  to V
- Add (v<sup>r</sup><sub>i</sub>, v<sup>s</sup><sub>j</sub>) to E whenever r ≠ s and l<sup>r</sup><sub>i</sub> is not the negation of l<sup>s</sup><sub>j</sub> (l<sup>r</sup><sub>i</sub> is and l<sup>s</sup><sub>j</sub> are consistent)
- Suppose that  $\phi$  is satisfiable; then:
  - The interpretation that makes  $\phi$  true makes at least one literal  $I_i^r$  per clause true
  - The vertex  $v_i^r$  is connected to all the other vertices  $v_j^s$  that make the other clauses true (these are all consistent with each other)
  - So the vertices  $v_i^r$  form a clique (of size k)



### • 3-SAT is NP-complete

- Hint: any clause  $x_1 \lor x_2 \lor \cdots \lor x_n$  is logically equivalent with
  - $(\mathbf{X}_1 \lor \mathbf{X}_2 \lor \mathbf{X}_2') \land (\overline{\mathbf{X}_2'} \lor \mathbf{X}_3 \lor \mathbf{X}_3') \land (\overline{\mathbf{X}_3'} \lor \mathbf{X}_4 \lor \mathbf{X}_4') \land \cdots \land (\overline{\mathbf{X}_{n-2}'} \lor \mathbf{X}_{n-1} \lor \mathbf{X}_n)$
- CLIQUE = { $(G = (V, E), k) : k \ge 2$  : there exists a clique *C* of *V* with |C| = k}

Membership in  $\mathcal{NP}$  and 3-SAT  $\leq_P \mathsf{CLIQUE} \Rightarrow \mathsf{CLIQUE} \in \mathcal{NPC}$ 

- Start from  $\phi = C_1 \land C_2 \land \cdots \land C_k$ , construct G = (V, E)
- Start with  $V = \emptyset$  and  $E = \emptyset$
- For each clause  $C_r = l_1^r \vee l_2^r \vee l_3^r$  add vertices  $v_1^r$ ,  $v_2^r$ , and  $v_3^r$  to V
- Add (v<sup>r</sup><sub>i</sub>, v<sup>s</sup><sub>j</sub>) to E whenever r ≠ s and l<sup>r</sup><sub>i</sub> is not the negation of l<sup>s</sup><sub>j</sub> (l<sup>r</sup><sub>i</sub> is and l<sup>s</sup><sub>j</sub> are consistent)
- Suppose that  $\phi$  is satisfiable; then:
  - The interpretation that makes  $\phi$  true makes at least one literal  $l_i^r$  per clause true
  - The vertex v<sup>s</sup><sub>i</sub> is connected to all the other vertices v<sup>s</sup><sub>j</sub> that make the other clauses true (these are all consistent with each other)
  - So the vertices  $v_i^r$  form a clique (of size k)
- Suppose that *G* has a clique *C* of size *k*; then:
  - C contains exactly one vertex per clause
  - Assigning  $\top$  to every literal  $l_i^r$  for which  $v_i^r \in C$  is possible (all are consistent with each other)
  - $\bullet~$  The assignment makes  $\phi$  true so  $\phi$  is satisfiable



- A vertex cover of G = (V, E) is a set  $V' \subseteq V$  such that  $(u, v) \in E \Rightarrow u \in V' \lor v \in V'$
- VERTEX-COVER = {(G = (V, E), k) : G has a vertex cover of size k} Membership in  $\mathcal{NP}$  and CLIQUE  $\leq_P$  VERTEX-COVER  $\Rightarrow$ VERTEX-COVER  $\in \mathcal{NPC}$



- A vertex cover of G = (V, E) is a set  $V' \subseteq V$  such that  $(u, v) \in E \Rightarrow u \in V' \lor v \in V'$
- VERTEX-COVER = {(G = (V, E), k) : G has a vertex cover of size k} Membership in  $\mathcal{NP}$  and CLIQUE  $\leq_P$  VERTEX-COVER  $\Rightarrow$ VERTEX-COVER  $\in \mathcal{NPC}$ 
  - Start from  $(G = (V, E), k) \in CLIQUE$
  - Compute  $\overline{G} = (V, \overline{E})$  where  $\overline{E} = (V \times V) \setminus E$  (the complement of *G*)
  - Then  $(G, k) \in \mathsf{CLIQUE}$  iff  $(\overline{G}, |V| k) \in \mathsf{VERTEX}\text{-}\mathsf{COVER}$



- A vertex cover of G = (V, E) is a set  $V' \subseteq V$  such that  $(u, v) \in E \Rightarrow u \in V' \lor v \in V'$
- VERTEX-COVER = {(G = (V, E), k) : G has a vertex cover of size k} Membership in  $\mathcal{NP}$  and CLIQUE  $\leq_P$  VERTEX-COVER  $\Rightarrow$ VERTEX-COVER  $\in \mathcal{NPC}$ 
  - Start from  $(G = (V, E), k) \in CLIQUE$
  - Compute  $\overline{G} = (V, \overline{E})$  where  $\overline{E} = (V \times V) \setminus E$  (the complement of *G*)
  - Then  $(G, k) \in \mathsf{CLIQUE}$  iff  $(\overline{G}, |V| k) \in \mathsf{VERTEX}\text{-}\mathsf{COVER}$
  - Suppose that G has a clique C, |C| = k; then:
    - $(u, v) \notin E$  means that u and v cannot be both in C
    - That is,  $V \setminus C$  covers every edge  $(u, v) \notin E$  that is, every vertex  $(u, v) \in \overline{E}$
    - Therefore  $V \setminus C$  is a vertex cover for  $\overline{G}$  (of size |V| k)



- A vertex cover of G = (V, E) is a set  $V' \subseteq V$  such that  $(u, v) \in E \Rightarrow u \in V' \lor v \in V'$
- VERTEX-COVER = {(G = (V, E), k) : G has a vertex cover of size k} Membership in  $\mathcal{NP}$  and CLIQUE  $\leq_P$  VERTEX-COVER  $\Rightarrow$ VERTEX-COVER  $\in \mathcal{NPC}$ 
  - Start from  $(G = (V, E), k) \in CLIQUE$
  - Compute  $\overline{G} = (V, \overline{E})$  where  $\overline{E} = (V \times V) \setminus E$  (the complement of *G*)
  - Then  $(G, k) \in \mathsf{CLIQUE}$  iff  $(\overline{G}, |V| k) \in \mathsf{VERTEX}\text{-}\mathsf{COVER}$
  - Suppose that G has a clique C, |C| = k; then:
    - $(u, v) \notin E$  means that u and v cannot be both in C
    - That is,  $V \setminus C$  covers every edge  $(u, v) \notin E$  that is, every vertex  $(u, v) \in \overline{E}$
    - Therefore  $V \setminus C$  is a vertex cover for  $\overline{G}$  (of size |V| k)
  - Suppose that  $\overline{G}$  has a vertex cover V' with |V'| = |V| k; then:
    - $(u, v) \in \overline{E} \Rightarrow u \in V' \lor v \in V'$
    - Contrapositive:  $u \notin V' \land v \notin V' \Rightarrow (u, v) \notin \overline{E}$
    - That is,  $u \in V \setminus V' \land v \in V \setminus V' \Rightarrow (u, v) \in E$
    - So  $V \setminus V'$  is a clique of *G* (or size *k*)

### HAMILTONIAN CYCLE

- HAMILTONIAN-CYCLE = {G = (V, E) : G is Hamiltonian} Membership in  $\mathcal{NP}$  and VERTEX-COVER  $\leq_P$  HAMILTONIAN-CYCLE  $\Rightarrow$ HAMILTONIAN-CYCLE  $\in \mathcal{NPC}$ 
  - Given (G = (V, E), k) construct G' = (V', E')
  - For each  $(u, v) \in E$  we use the widget  $W_{uv}$  to the right.
  - A widget can only connect to the rest of the graph through [*u*, *v*, 1], [*u*, *v*, 6], [*v*, *u*, 1], and [*v*, *u*, 6]
  - Thus there are only three ways to traverse a widget as part of a Hamiltonian cycle
  - We also use the selector vertices  $s_1, s_2, \ldots, s_k$
  - For each  $u \in V$  and all the vertices  $u^{(1)}, \ldots, u^{(du)}$  adjacent to u in G we add  $([u, u^{(i)}, 6], [u, u^{(i+1)}, 1])$  to  $G', 1 \le i \le du 1$ 
    - These form a "path of widgets" that include all the widgets for the edges incident on *u*
    - Useful to start such a part from a member of the vertex cover
  - We add the vertices  $(s_j, [u, u^{(1)}, 1])$  and  $(s_j, [u, u^{du}, 6])$  for all  $u \in V$  and  $1 \le j \le k$ 
    - These complete a cycle (combined with the path of widgets) but only for the members of the vertex cover



